

Stability theory for concrete categories

Sebastien Vasey

Harvard University

December 9, 2019

Westfälische Wilhelms-Universität
Münster

A puzzle

If six students come to a party, then three of them all know each other, or three of them all do not know each other. More formally and generally:

Theorem (Ramsey, 1930)

For any natural number k , there exists a natural number n such that:

$$n \rightarrow (k)_2$$

A puzzle

If six students come to a party, then three of them all know each other, or three of them all do not know each other. More formally and generally:

Theorem (Ramsey, 1930)

For any natural number k , there exists a natural number n such that:

$$n \rightarrow (k)_2$$

The notation is due to Erdős and Rado. It means: for any set X with at least n elements and any coloring $F : \binom{X}{2} \rightarrow \{0, 1\}$, there exists $H \subseteq X$ with $|H| = k$ so that $F \upharpoonright \binom{H}{2}$ is constant (we call H a *homogeneous set* for F).

A puzzle

If six students come to a party, then three of them all know each other, or three of them all do not know each other. More formally and generally:

Theorem (Ramsey, 1930)

For any natural number k , there exists a natural number n such that:

$$n \rightarrow (k)_2$$

The notation is due to Erdős and Rado. It means: for any set X with at least n elements and any coloring $F : \binom{X}{2} \rightarrow \{0, 1\}$, there exists $H \subseteq X$ with $|H| = k$ so that $F \upharpoonright \binom{H}{2}$ is constant (we call H a *homogeneous set* for F).

If $k = 3$, $n = 6$ suffices. If $k = 5$, the optimal value of n is not known.

An infinite variation on the puzzle

If an infinite number of students come to a party, then infinitely-many all know each other or infinitely-many all do not know each other.

More formally:

Theorem (Ramsey, 1930)

$$\aleph_0 \rightarrow (\aleph_0)_2$$

An infinite variation on the puzzle

If an infinite number of students come to a party, then infinitely-many all know each other or infinitely-many all do not know each other.

More formally:

Theorem (Ramsey, 1930)

$$\aleph_0 \rightarrow (\aleph_0)_2$$

Said differently, for any set X with $|X| \geq \aleph_0$ and any coloring $F : \binom{X}{2} \rightarrow \{0, 1\}$, there exists $H \subseteq X$ so that $|H| = \aleph_0$ and $F \upharpoonright \binom{H}{2}$ is constant.

An infinite variation on the puzzle

If an infinite number of students come to a party, then infinitely-many all know each other or infinitely-many all do not know each other.

More formally:

Theorem (Ramsey, 1930)

$$\aleph_0 \rightarrow (\aleph_0)_2$$

Said differently, for any set X with $|X| \geq \aleph_0$ and any coloring $F : \binom{X}{2} \rightarrow \{0, 1\}$, there exists $H \subseteq X$ so that $|H| = \aleph_0$ and $F \upharpoonright \binom{H}{2}$ is constant.

The theorem does *not* rule out a party with uncountably-many students where all friends/strangers groups (= homogeneous sets) are countable.

The set theorist's dream

For any infinite cardinal λ , if λ students come to a party, then there is a group of λ -many that all know each other or a group of λ -many that all do not know each other. That is:

$$\lambda \rightarrow (\lambda)_2$$

The set theorist's dream

For any infinite cardinal λ , if λ students come to a party, then there is a group of λ -many that all know each other or a group of λ -many that all do not know each other. That is:

$$\lambda \rightarrow (\lambda)_2$$

This is wrong for most cardinals λ (Sierpiński).

A counterexample with an infinite number of colors

Proposition (Erdős-Kakutani)

$$|\mathbb{R}| \not\leq (3)_{\aleph_0}$$

A counterexample with an infinite number of colors

Proposition (Erdős-Kakutani)

$$|\mathbb{R}| \not\rightarrow (3)_{\aleph_0}$$

Proof.

Take $F(\{x, y\}) =$ some rational between x and y . A set H homogeneous for F cannot contain three elements! □

A counterexample with an infinite number of colors

Proposition (Erdős-Kakutani)

$$|\mathbb{R}| \not\approx (3)^{\aleph_0}$$

Proof.

Take $F(\{x, y\}) =$ some rational between x and y . A set H homogeneous for F cannot contain three elements! □

In the reals, a countable set allows one to distinguish uncountably-many points. There are however many structures where this is not the case.

The set theorist's dream in the complex numbers

Proposition

If $F : [\mathbb{C}]^2 \rightarrow \{0, 1\}$ is a coloring of the unordered pairs of complex numbers in two colors *such that* $F(\{f(x), f(y)\}) = F(\{x, y\})$ *for any field automorphism* f *of* \mathbb{C} , then F has a homogeneous set of cardinality $|\mathbb{C}|$.

The set theorist's dream in the complex numbers

Proposition

If $F : [\mathbb{C}]^2 \rightarrow \{0, 1\}$ is a coloring of the unordered pairs of complex numbers in two colors *such that* $F(\{f(x), f(y)\}) = F(\{x, y\})$ *for any field automorphism* f *of* \mathbb{C} , then F has a homogeneous set of cardinality $|\mathbb{C}|$.

Proof.

Any transcendence basis for \mathbb{C} does the job. □

The set theorist's dream in the complex numbers

Proposition

If $F : [\mathbb{C}]^2 \rightarrow \{0, 1\}$ is a coloring of the unordered pairs of complex numbers in two colors *such that* $F(\{f(x), f(y)\}) = F(\{x, y\})$ for any field automorphism f of \mathbb{C} , then F has a homogeneous set of cardinality $|\mathbb{C}|$.

Proof.

Any transcendence basis for \mathbb{C} does the job. □

This proves $|\mathbb{C}| \rightarrow |\mathbb{C}|_2$ but “relativized to \mathbb{C} ” (for colorings preserved by automorphisms).

Types

A category \mathbf{K} has *amalgamation* if any diagram of the form $B \leftarrow A \rightarrow C$ can be completed to a commuting square (no universal property required – this is much weaker than pushouts).

Types

A category \mathbf{K} has *amalgamation* if any diagram of the form $B \leftarrow A \rightarrow C$ can be completed to a commuting square (no universal property required – this is much weaker than pushouts).

Definition

Given a concrete category \mathbf{K} with amalgamation and an object A of \mathbf{K} , a *type over A* is just a pair $(x, A \xrightarrow{f} B)$, with $x \in B$. Two types $(x, A \xrightarrow{f} B)$, $(y, A \xrightarrow{g} C)$ are considered *the same* if there exists maps h_1, h_2 so that $h_1(x) = h_2(y)$ and the following diagram commutes:

$$\begin{array}{ccc} B & \xrightarrow{\quad h_1 \quad} & D \\ f \uparrow & & \uparrow h_2 \\ A & \xrightarrow{\quad g \quad} & C \end{array}$$

Types in fields, linear orders, and graphs

Essentially, one can think of types over a fixed base A as the orbits of an automorphism group fixing A .

Types in fields, linear orders, and graphs

Essentially, one can think of types over a fixed base A as the orbits of an automorphism group fixing A .

The base matters. For example in the category of fields, $e^{\frac{1}{3}}$ and $e^{\frac{1}{2}}$ have the same type over \mathbb{Q} but not the same type over $\mathbb{Q}(e)$.

Types in fields, linear orders, and graphs

Essentially, one can think of types over a fixed base A as the orbits of an automorphism group fixing A .

The base matters. For example in the category of fields, $e^{\frac{1}{3}}$ and $e^{\frac{1}{2}}$ have the same type over \mathbb{Q} but not the same type over $\mathbb{Q}(e)$.

In the category of fields, there are at most $\max(|A|, \aleph_0)$ types over every object A (just one type for the transcendental element).

Types in fields, linear orders, and graphs

Essentially, one can think of types over a fixed base A as the orbits of an automorphism group fixing A .

The base matters. For example in the category of fields, $e^{\frac{1}{3}}$ and $e^{\frac{1}{2}}$ have the same type over \mathbb{Q} but not the same type over $\mathbb{Q}(e)$.

In the category of fields, there are at most $\max(|A|, \aleph_0)$ types over every object A (just one type for the transcendental element).

In the category of linear orders, there are $|\mathbb{R}|$ types over \mathbb{Q} . In general, types correspond to Dedekind cuts.

Types in fields, linear orders, and graphs

Essentially, one can think of types over a fixed base A as the orbits of an automorphism group fixing A .

The base matters. For example in the category of fields, $e^{\frac{1}{3}}$ and $e^{\frac{1}{2}}$ have the same type over \mathbb{Q} but not the same type over $\mathbb{Q}(e)$.

In the category of fields, there are at most $\max(|A|, \aleph_0)$ types over every object A (just one type for the transcendental element).

In the category of linear orders, there are $|\mathbb{R}|$ types over \mathbb{Q} . In general, types correspond to Dedekind cuts.

In the category of graphs with induced subgraph embeddings, there are at least $2^{|V(G)|}$ types over any graph G .

Types in fields, linear orders, and graphs

Essentially, one can think of types over a fixed base A as the orbits of an automorphism group fixing A .

The base matters. For example in the category of fields, $e^{\frac{1}{3}}$ and $e^{\frac{1}{2}}$ have the same type over \mathbb{Q} but not the same type over $\mathbb{Q}(e)$.

In the category of fields, there are at most $\max(|A|, \aleph_0)$ types over every object A (just one type for the transcendental element).

In the category of linear orders, there are $|\mathbb{R}|$ types over \mathbb{Q} . In general, types correspond to Dedekind cuts.

In the category of graphs with induced subgraph embeddings, there are at least $2^{|V(G)|}$ types over any graph G .

If we restrict to graphs with finite degrees, we obtain again at most $\max(|V(G)|, \aleph_0)$ types over G

Definition (Stability)

A concrete category \mathbf{K} is *stable in* λ if there are at most λ -many types over any object of cardinality λ . *Stable* means stable in an unbounded class, and *superstable* means stable on an end-segment.

Definition (Stability)

A concrete category \mathbf{K} is *stable in* λ if there are at most λ -many types over any object of cardinality λ . *Stable* means stable in an unbounded class, and *superstable* means stable on an end-segment.

- ▶ The category of graphs with induced subgraph embeddings and the category of linear orders are unstable. The category of fields is superstable.

Definition (Stability)

A concrete category \mathbf{K} is *stable in* λ if there are at most λ -many types over any object of cardinality λ . *Stable* means stable in an unbounded class, and *superstable* means stable on an end-segment.

- ▶ The category of graphs with induced subgraph embeddings and the category of linear orders are unstable. The category of fields is superstable.
- ▶ (Eklof 1971, Mazari-Armida) The category of R -modules with embeddings is always stable, and superstable if and only if R is left Noetherian.

Definition (Stability)

A concrete category \mathbf{K} is *stable in* λ if there are at most λ -many types over any object of cardinality λ . *Stable* means stable in an unbounded class, and *superstable* means stable on an end-segment.

- ▶ The category of graphs with induced subgraph embeddings and the category of linear orders are unstable. The category of fields is superstable.
- ▶ (Eklof 1971, Mazari-Armida) The category of R -modules with embeddings is always stable, and superstable if and only if R is left Noetherian.
- ▶ (Kucera and Mazari-Armida) The category of R -modules with pure embeddings is always stable, and superstable if and only if R is left pure-semisimple.

The set theorist's dream in stable AECs

Theorem (V.)

If \mathbf{K} is an abstract elementary class with amalgamation and \mathbf{K} is stable in λ , then:

$$\lambda^+ \xrightarrow{\mathbf{K}} (\lambda^+)_{\lambda}$$

Here λ^+ is the cardinal right after λ .

The set theorist's dream in stable AECs

Theorem (V.)

If \mathbf{K} is an abstract elementary class with amalgamation and \mathbf{K} is stable in λ , then:

$$\lambda^+ \xrightarrow{\mathbf{K}} (\lambda^+)_{\lambda}$$

Here λ^+ is the cardinal right after λ .

The partition notation means that given objects $A \rightarrow B$ in \mathbf{K} with $|A| = \lambda$, $|B| = \lambda^+$, if F is a coloring of pairs from B in λ -many colors so that any two pairs with the same type over A have the same color, then we can find a homogeneous set for F of cardinality λ^+ .

What an abstract elementary class (AEC) is will be explained in the next slide. All the examples given so far are AECs.

Theorem (V.)

If \mathbf{K} is an abstract elementary class with amalgamation and \mathbf{K} is stable in λ , then:

$$\lambda^+ \xrightarrow{\mathbf{K}} (\lambda^+)_\lambda$$

Definition (Shelah, late 1970s)

An abstract elementary class (AEC) is a concrete category \mathbf{K} satisfying the following conditions:

- ▶ All morphisms are concrete monomorphisms (injections).
- ▶ \mathbf{K} has concrete directed colimits (also known as direct limits – basically closure under unions of increasing chains).
- ▶ (Smallness condition) Every object is a directed colimit of a fixed set of “small” subobjects.

Examples of abstract elementary classes

All the categories mentioned before are AECs.

Examples of abstract elementary classes

All the categories mentioned before are AECs.

Noetherian rings do not form an AEC: the chain

$\mathbb{Z} \rightarrow \mathbb{Z}[x_1] \rightarrow \mathbb{Z}[x_1, x_2] \rightarrow \dots$ does not have a colimit.

Examples of abstract elementary classes

All the categories mentioned before are AECs.

Noetherian rings do not form an AEC: the chain

$\mathbb{Z} \rightarrow \mathbb{Z}[x_1] \rightarrow \mathbb{Z}[x_1, x_2] \rightarrow \dots$ does not have a colimit.

Any AEC is an accessible category: a category with all sufficiently directed colimits satisfying a certain smallness condition.

Abstract elementary classes and logic

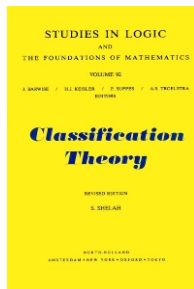
For any set T of first-order sentences, the category $\text{Mod}(T)$ of models of T forms an AEC (the morphisms are the functions preserving all formulas).

Abstract elementary classes and logic

For any set T of first-order sentences, the category $\text{Mod}(T)$ of models of T forms an AEC (the morphisms are the functions preserving all formulas).

We will call such a category a *first-order class*. It is one of the basic objects of study in model theory.

Stability theory was developed for first-order classes first, by Saharon Shelah.



Beyond first-order classes

There are some good reasons to look at more general classes. On the logic side, one can consider the infinitary logic $\mathbb{L}_{\infty, \omega}$, where infinite conjunctions and disjunctions are allowed (this logic also yields AECs, and usually any problem that is hard for AECs is hard already for this logic).

For example, we can say:

$$(\neg \exists x)(x > 1 \wedge x > 1 + 1 \wedge x > 1 + 1 + 1 \wedge \dots)$$

Beyond first-order classes

There are some good reasons to look at more general classes. On the logic side, one can consider the infinitary logic $\mathbb{L}_{\infty, \omega}$, where infinite conjunctions and disjunctions are allowed (this logic also yields AECs, and usually any problem that is hard for AECs is hard already for this logic).

For example, we can say:

$$(\neg \exists x)(x > 1 \wedge x > 1 + 1 \wedge x > 1 + 1 + 1 \wedge \dots)$$

First-order classes are important, because of the *compactness theorem*: if all finite subsets of a given theory have a model, then the whole theory has a model. This is powerful (one can use it to build models for nonstandard analysis) but means that many interesting categories are not first-order.

Beyond first-order classes

There are some good reasons to look at more general classes. On the logic side, one can consider the infinitary logic $\mathbb{L}_{\infty, \omega}$, where infinite conjunctions and disjunctions are allowed (this logic also yields AECs, and usually any problem that is hard for AECs is hard already for this logic).

For example, we can say:

$$(\neg \exists x)(x > 1 \wedge x > 1 + 1 \wedge x > 1 + 1 + 1 \wedge \dots)$$

First-order classes are important, because of the *compactness theorem*: if all finite subsets of a given theory have a model, then the whole theory has a model. This is powerful (one can use it to build models for nonstandard analysis) but means that many interesting categories are not first-order.

Also, the *morphisms* of first-order classes are not so natural.

Examples

- ▶ The category of algebraically closed fields (with field homomorphisms) is first-order.

Examples

- ▶ The category of algebraically closed fields (with field homomorphisms) is first-order.
- ▶ However the category of fields is not: while the axioms of fields are first-order, the embedding $\mathbb{Q} \rightarrow \mathbb{R}$ does not preserve all formulas (consider $(\exists x)(x \cdot x = 2)$).

Examples

- ▶ The category of algebraically closed fields (with field homomorphisms) is first-order.
- ▶ However the category of fields is not: while the axioms of fields are first-order, the embedding $\mathbb{Q} \rightarrow \mathbb{R}$ does not preserve all formulas (consider $(\exists x)(x \cdot x = 2)$).
- ▶ In fact none of the other examples given so far are first-order.

Eventual categoricity

Theorem (Morley, 1965)

A countable set of first-order sentences with a single model of *some* uncountable cardinality has a single model in *all* uncountable cardinalities.

Eventual categoricity

Theorem (Morley, 1965)

A countable set of first-order sentences with a single model of *some* uncountable cardinality has a single model in *all* uncountable cardinalities.

Morley's theorem was generalized to all first-order classes by Shelah (1974). He then asked about infinitary logics, and introduced AECs as a general framework to study the following question (*Shelah's eventual categoricity conjecture*).

Conjecture (Shelah, late seventies)

An AEC with a single object of *some* high-enough cardinality has a single object in *all* high-enough cardinalities.

Eventual categoricity

Theorem (Morley, 1965)

A countable set of first-order sentences with a single model of *some* uncountable cardinality has a single model in *all* uncountable cardinalities.

Morley's theorem was generalized to all first-order classes by Shelah (1974). He then asked about infinitary logics, and introduced AECs as a general framework to study the following question (*Shelah's eventual categoricity conjecture*).

Conjecture (Shelah, late seventies)

An AEC with a single object of *some* high-enough cardinality has a single object in *all* high-enough cardinalities.

One motivating goal is to develop stability theory for AECs.

Shelah's eventual categoricity conjecture

Conjecture (Shelah, late seventies)

An AEC with a single object of *some* high-enough cardinality has a single object in *all* high-enough cardinalities.

Shelah's eventual categoricity conjecture

Conjecture (Shelah, late seventies)

An AEC with a single object of *some* high-enough cardinality has a single object in *all* high-enough cardinalities.

The conjecture is still open.

Shelah's eventual categoricity conjecture

Conjecture (Shelah, late seventies)

An AEC with a single object of *some* high-enough cardinality has a single object in *all* high-enough cardinalities.

The conjecture is still open.

Partial approximations before my thesis include: Shelah 1983, Makkai-Shelah 1990, Shelah 1999, Shelah-Villaveces 1999, VanDieren 2006, Grossberg-VanDieren 2006, Shelah 2009, Hyttinen-Kesälä 2011, Boney 2014.



Toward Shelah's eventual categoricity conjecture

Theorem (V. 2017)

Shelah's eventual categoricity conjecture is true for universal AECs.

Toward Shelah's eventual categoricity conjecture

Theorem (V. 2017)

Shelah's eventual categoricity conjecture is true for universal AECs.

Theorem (Shelah-V.)

Shelah's eventual categoricity conjecture is true for all AECs, assuming a large cardinal axiom (there exists a proper class of strongly compact cardinals).

Toward Shelah's eventual categoricity conjecture

Theorem (V. 2017)

Shelah's eventual categoricity conjecture is true for universal AECs.

Theorem (Shelah-V.)

Shelah's eventual categoricity conjecture is true for all AECs, assuming a large cardinal axiom (there exists a proper class of strongly compact cardinals).

Theorem (V. 2019)

Assuming the GCH, Shelah's eventual categoricity conjecture is true for AECs with amalgamation. In this case one can list all possibilities for the class of cardinals in which the category has a unique object.

A characterization of stability

Theorem (V. 2016, Boney)

A tame AEC \mathbf{K} with amalgamation is stable if and only if it does not have the “order property”: any faithful functor $\mathbf{Lin} \xrightarrow{F} \mathbf{K}$ factors through the forgetful functor.

$$\begin{array}{ccc} \mathbf{Lin} & \xrightarrow{F} & \mathbf{K} \\ \downarrow U & \nearrow \text{dotted} & \\ \mathbf{Set} & & \end{array}$$

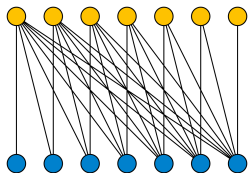
Order in graphs: an intermission

Graphs with induced subgraph embeddings are unstable, so they must have the order property: where is it?

Order in graphs: an intermission

Graphs with induced subgraph embeddings are unstable, so they must have the order property: where is it?

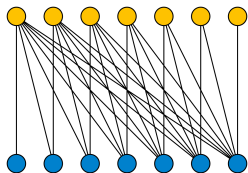
It is given by a half graph: for any linear ordering L , consider the bipartite graph on $L \sqcup L$ where we put an edge from i to j if only if $i \leq j$ (the picture below is for $L = \{1, 2, 3, 4, 5, 6, 7\}$):



Order in graphs: an intermission

Graphs with induced subgraph embeddings are unstable, so they must have the order property: where is it?

It is given by a half graph: for any linear ordering L , consider the bipartite graph on $L \sqcup L$ where we put an edge from i to j if only if $i \leq j$ (the picture below is for $L = \{1, 2, 3, 4, 5, 6, 7\}$):



Graphs omitting half graphs are studied in finite combinatorics too (Malliaris-Shelah, *Regularity lemmas for stable graphs*. TAMS 2014).

Stable independence

The proofs of the eventual categoricity conjecture, of the stability spectrum theorem, and of the partition theorem $\lambda^+ \xrightarrow{\mathbf{K}} (\lambda^+)_{\lambda}$ involve describing what it means for a type to be “determined” over a small base. This is called forking in the first-order context, and is the key tool developed by Shelah in his classification theory book. It generalizes algebraic independence in fields.

Stable independence

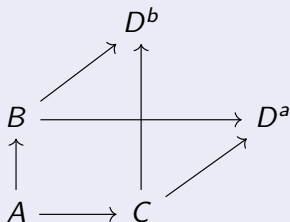
The proofs of the eventual categoricity conjecture, of the stability spectrum theorem, and of the partition theorem $\lambda^+ \xrightarrow{\mathbf{K}} (\lambda^+)_{\lambda}$ involve describing what it means for a type to be “determined” over a small base. This is called forking in the first-order context, and is the key tool developed by Shelah in his classification theory book. It generalizes algebraic independence in fields.

Unfortunately Shelah’s definition is syntactic, hard to describe, and some properties depend on compactness. With my collaborators, we found a completely category-theoretic definition.

Definition (Equivalence of amalgam)

Consider a diagram: $B \leftarrow A \rightarrow C$

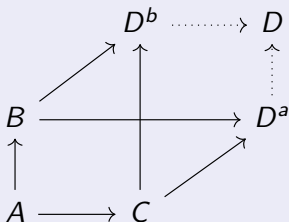
Two amalgams $B \rightarrow D^a \leftarrow C$, $B \rightarrow D^b \leftarrow C$ of this diagram are *equivalent* if there exists D and arrows making the following diagram commute:



Definition (Equivalence of amalgam)

Consider a diagram: $B \leftarrow A \rightarrow C$

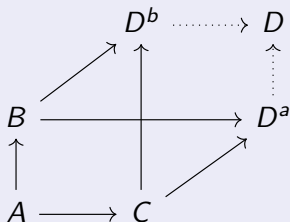
Two amalgams $B \rightarrow D^a \leftarrow C$, $B \rightarrow D^b \leftarrow C$ of this diagram are *equivalent* if there exists D and arrows making the following diagram commute:



Definition (Equivalence of amalgam)

Consider a diagram: $B \leftarrow A \rightarrow C$

Two amalgams $B \rightarrow D^a \leftarrow C$, $B \rightarrow D^b \leftarrow C$ of this diagram are *equivalent* if there exists D and arrows making the following diagram commute:



Example: in \mathbf{Set}_{mono} , $\{0\}$ and $\{1\}$ have two non-equivalent amalgams over \emptyset : $\{0, 1\}$ and $\{1\}$ (with the expected morphisms).

Definition (Stable independence; Lieberman-Rosický-V., 2019)

A *stable independence notion* is a class of squares (called *independent squares*, marked with \perp) such that:

Definition (Stable independence; Lieberman-Rosický-V., 2019)

A *stable independence notion* is a class of squares (called *independent squares*, marked with \perp) such that:

1. Independent squares are closed under equivalence of amalgam.

Definition (Stable independence; Lieberman-Rosický-V., 2019)

A *stable independence notion* is a class of squares (called *independent squares*, marked with \perp) such that:

1. Independent squares are closed under equivalence of amalgam.
2. Existence: any span can be amalgamated to an independent square.

Definition (Stable independence; Lieberman-Rosický-V., 2019)

A *stable independence notion* is a class of squares (called *independent squares*, marked with \perp) such that:

1. Independent squares are closed under equivalence of amalgam.
2. Existence: any span can be amalgamated to an independent square.
3. Uniqueness: any two *independent* amalgam of the same span are equivalent.

Definition (Stable independence; Lieberman-Rosický-V., 2019)

A *stable independence notion* is a class of squares (called *independent squares*, marked with \perp) such that:

1. Independent squares are closed under equivalence of amalgam.
2. Existence: any span can be amalgamated to an independent square.
3. Uniqueness: any two *independent* amalgam of the same span are equivalent.
4. Symmetry:

$$\begin{array}{ccc} B & \longrightarrow & D \\ \uparrow & \perp & \uparrow \\ A & \longrightarrow & C \end{array} \Rightarrow \begin{array}{ccc} C & \longrightarrow & D \\ \uparrow & \perp & \uparrow \\ A & \longrightarrow & B \end{array}$$

Definition (stable independence notion - continued)

5. Transitivity:

$$\begin{array}{ccccc} B & \longrightarrow & D & \longrightarrow & F \\ \uparrow & & \uparrow & & \uparrow \\ A & \longrightarrow & C & \longrightarrow & E \end{array} \quad \Downarrow \quad \begin{array}{ccccc} B & \longrightarrow & & \longrightarrow & F \\ \uparrow & & & & \uparrow \\ A & \longrightarrow & & \longrightarrow & E \end{array}$$

Definition (stable independence notion - continued)

5. Transitivity:

$$\begin{array}{ccccc} B & \longrightarrow & D & \longrightarrow & F \\ \uparrow & & \downarrow & & \uparrow \\ A & \longrightarrow & C & \longrightarrow & E \end{array} \Rightarrow \begin{array}{ccccc} B & \longrightarrow & & \longrightarrow & F \\ \uparrow & & & & \uparrow \\ A & \longrightarrow & & \longrightarrow & E \end{array}$$

6. Accessibility: the category whose objects are arrows and whose morphisms are independent squares is accessible. This implies that any arrow can be “filtered” in an independent way:

$$\begin{array}{ccc} M & \longrightarrow & N \\ \uparrow \cdots & & \downarrow \cdots \\ M_i & \cdots \longrightarrow & N_i \end{array}$$

Theorem (Canonicity theorem; Lieberman-Rosický-V. 2019)

A category with directed colimits (in particular an AEC) has *at most one* stable independence notion.

Theorem (Canonicity theorem; Lieberman-Rosický-V. 2019)

A category with directed colimits (in particular an AEC) has *at most one* stable independence notion.

In any accessible category with pushouts, the class of all squares forms a stable independence notion.

Theorem (Canonicity theorem; Lieberman-Rosický-V. 2019)

A category with directed colimits (in particular an AEC) has *at most one* stable independence notion.

In any accessible category with pushouts, the class of all squares forms a stable independence notion.

In very simple AECs, like the AEC of vector spaces or sets, stable independence is given by pullback squares. In the AEC of fields, the definition is essentially given by algebraic independence.

Theorem (Canonicity theorem; Lieberman-Rosický-V. 2019)

A category with directed colimits (in particular an AEC) has *at most one* stable independence notion.

In any accessible category with pushouts, the class of all squares forms a stable independence notion.

In very simple AECs, like the AEC of vector spaces or sets, stable independence is given by pullback squares. In the AEC of fields, the definition is essentially given by algebraic independence.

Theorem (Lieberman-Rosický-V. 2019)

An AEC with a stable independence notion has amalgamation, is tame, and is stable.

Certain converses are true too (for example in first-order classes, or assuming large cardinals).

Stable independence and cofibrant generation

Theorem (Lieberman-Rosický-V.)

Let \mathcal{K} be an accessible, bicomplete category (like the category of R -modules with homomorphisms). Let \mathcal{M} be a class of morphisms of \mathcal{K} such that:

1. \mathcal{M} contains all isomorphisms, is closed under transfinite compositions, pushouts, and retracts.
2. The induced category $\mathcal{K}_{\mathcal{M}}$ is accessible and closed under directed colimits in \mathcal{K} .
3. \mathcal{M} is coherent: if $A \xrightarrow{f} B \xrightarrow{g} C$, $g, gf \in \mathcal{M}$, then $f \in \mathcal{M}$.

Stable independence and cofibrant generation

Theorem (Lieberman-Rosický-V.)

Let \mathcal{K} be an accessible, bicomplete category (like the category of R -modules with homomorphisms). Let \mathcal{M} be a class of morphisms of \mathcal{K} such that:

1. \mathcal{M} contains all isomorphisms, is closed under transfinite compositions, pushouts, and retracts.
2. The induced category $\mathcal{K}_{\mathcal{M}}$ is accessible and closed under directed colimits in \mathcal{K} .
3. \mathcal{M} is coherent: if $A \xrightarrow{f} B \xrightarrow{g} C$, $g, gf \in \mathcal{M}$, then $f \in \mathcal{M}$.

Then $\mathcal{K}_{\mathcal{M}}$ has stable independence if and only if \mathcal{M} is cofibrantly generated (i.e. can be generated from a subset using transfinite compositions, pushouts, and retracts).

New examples of stable independence

Corollary (Lieberman-Rosický-V.)

1. The AEC of flat R -modules with flat morphisms (more generally, any AEC of “roots of Ext”) has stable independence.

New examples of stable independence

Corollary (Lieberman-Rosický-V.)

1. The AEC of flat R -modules with flat morphisms (more generally, any AEC of “roots of Ext”) has stable independence.
2. Any Grothendieck topos restricted to regular monos has stable independence.

New examples of stable independence

Corollary (Lieberman-Rosický-V.)

1. The AEC of flat R -modules with flat morphisms (more generally, any AEC of “roots of Ext”) has stable independence.
2. Any Grothendieck topos restricted to regular monos has stable independence.
3. Any Grothendieck abelian category restricted to monos has stable independence.

New examples of stable independence

Corollary (Lieberman-Rosický-V.)

1. The AEC of flat R -modules with flat morphisms (more generally, any AEC of “roots of Ext”) has stable independence.
2. Any Grothendieck topos restricted to regular monos has stable independence.
3. Any Grothendieck abelian category restricted to monos has stable independence.
4. Any Cisinski model category restricted to monos has stable independence.

Summary and future work

Stability theory studies universes where things are “locally generated”, and a nice infinite combinatorics is possible.

Summary and future work

Stability theory studies universes where things are “locally generated”, and a nice infinite combinatorics is possible.

It was developed for classes axiomatized by first-order theories by Shelah in the seventies.

Summary and future work

Stability theory studies universes where things are “locally generated”, and a nice infinite combinatorics is possible.

It was developed for classes axiomatized by first-order theories by Shelah in the seventies.

In hindsight, it seems this was too restrictive: many interesting categories are not first-order but still admit stability theory.

Summary and future work

Stability theory studies universes where things are “locally generated”, and a nice infinite combinatorics is possible.

It was developed for classes axiomatized by first-order theories by Shelah in the seventies.

In hindsight, it seems this was too restrictive: many interesting categories are not first-order but still admit stability theory.

The notion of stable independence is central to stability theory. The category-theoretic definition is simple, and it seems it should appear in more places: *where else can we find it?*

Summary and future work

Stability theory studies universes where things are “locally generated”, and a nice infinite combinatorics is possible.

It was developed for classes axiomatized by first-order theories by Shelah in the seventies.

In hindsight, it seems this was too restrictive: many interesting categories are not first-order but still admit stability theory.

The notion of stable independence is central to stability theory. The category-theoretic definition is simple, and it seems it should appear in more places: *where else can we find it?*

The category-theoretic definition of stable independence also naturally yields higher-dimensional generalizations (independent cubes). These are well known in model theory but the earlier definitions are ad-hoc and complicated. The goal is now to *develop a systematic theory, and also to find more examples.*

Thank you!

Some references:

- ▶ Sebastien Vasey, *Shelah's eventual categoricity conjecture in universal classes: part II*, *Selecta Mathematica* **23** (2017), no. 2, 1469–1506.
- ▶ Michael Lieberman, Jiří Rosický, and Sebastien Vasey, *Forking independence from the categorical point of view*, *Advances in Mathematics* **346** (2019), 719–772.
- ▶ Sebastien Vasey, *The categoricity spectrum of large abstract elementary classes with amalgamation*, *Selecta Mathematica* **25** (2019), no. 5, 65 (51 pages).
- ▶ Saharon Shelah and Sebastien Vasey, *Categoricity and multidimensional diagrams*, arXiv:1805.0629.
- ▶ Michael Lieberman, Jiří Rosický, and Sebastien Vasey, *Weak factorization systems and stable independence*, arXiv:1904.05691.
- ▶ Sebastien Vasey, *Accessible categories, set theory, and model theory: an invitation*, arXiv:1904.11307.